

# The Range of Random Walk Bridges

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# Acknowledgements

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# Presentation Outline

- Preliminaries
- Motivations
- Counting subgraphs
- Intro to Expanders
- *The Result*
- Proof (if we have time)

Antony Gormley's Quantum Cloud sculpture in London was designed by a computer using a random walk algorithm

## A **Random Walk Bridge** is a **Closed Random Walk**:

A walk which is **conditioned to return to its start vertex** at time  **$t$**

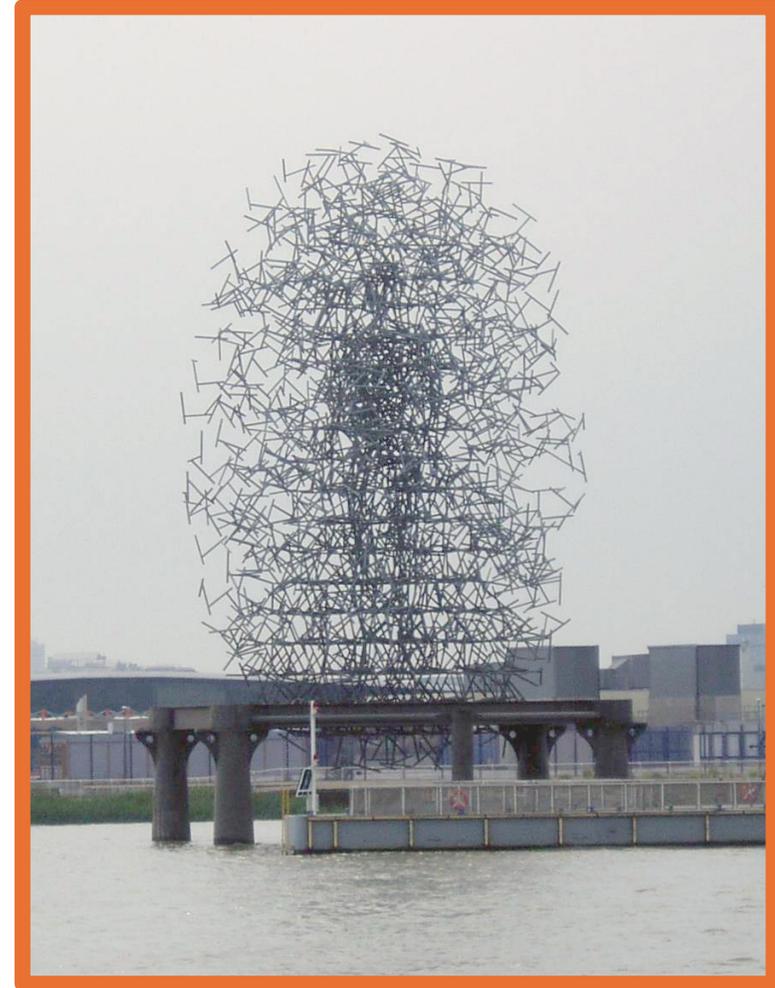
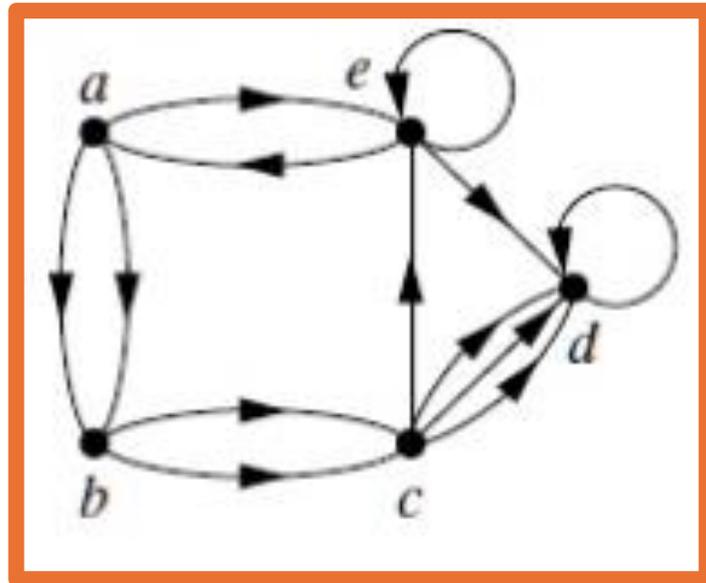


Image by Andy Roberts from East London, England - Flickr, CC BY 2.0,  
<https://commons.wikimedia.org/w/index.php?curid=448926>

(next vertex chosen uniformly)

In this project, we use a **simple random walk** which traverses a finite **bounded-degree graph** (where every vertex has **at most  $\Delta$  neighbours**)



A directed graph with loops and multi-edges

We assume that the graph is **undirected** and has **no loops or multi-edges**

Why these prerequisites?

**Simple** random walk → Avoids extreme cases

**Finite, bounded degree** → Useful bounds  
(on transition probabilities and the stationary distribution)

# Why this project?

Random walks have uses in countless algorithms<sup>1</sup>

- Determining Satisfiability
- Estimating information spreading
- Approximating the volume of convex bodies

1. Thomas Sauerwald, He Sun, and Danny Vagnozzi. 'The Support of Open Versus Closed Random Walks'.  
doi: 10.4230/LIPIcs.ICALP.2023.103

- Determining Connectedness
- Estimating network sizes and densities
- The voter model
- Graph exploration
- Analysis of Randomness Amplification
- Estimating load balancing
- Electrical networks
- Other things in geometry, group theory, etc.

Motivations continued...

**Open** random walks have many known results

There is currently far less research on **closed** random walks

From a paper<sup>1</sup> on **closed** random walks...

“...it is tempting to conjecture that on any bounded-degree **expander** graph, the lower bound on the **[range]** can be improved, possibly even to  $\Omega(t)$ , which would ... match the bound for open random walks”

1. Thomas Sauerwald, He Sun, and Danny Vagnozzi. 'The Support of Open Versus Closed Random Walks'.  
doi: 10.4230/LIPIcs.ICALP.2023.103

The **Range** of a Random Walk is the number of unique vertices it visits

The **range** of a walk is **at most linear** in the length of the walk

This means the range's long-term behaviour is at least linear in  $t$

Therefore, a lower bound of  **$\Omega(t)$**  could not be improved upon

We'll cover what 'expanders' are later...

# Counting Subgraphs

A result we'll use later

Later we will need to know an upper bound for the **number of connected sets of size  $s$  containing some fixed start vertex**

In this section, we will find such a bound

This method was found in the following paper;

Theo McKenzie, Peter M. R. Rasmussen, and Nikhil Srivastava. 'Support of Closed Walks and Second Eigenvalue Multiplicity of the Normalized Adjacency Matrix'. url: <https://arxiv.org/abs/2007.12819>

We may be tempted to find a surjection like this;

**Random walks  
of length  $s$   
starting from  $x$**

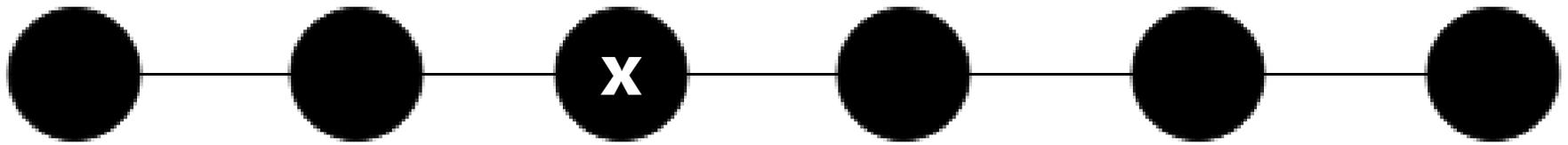


**Connected  
sets of size  
 $s$  around  $x$**

(we send a walk of length  $s$  to the set of vertices it visited)

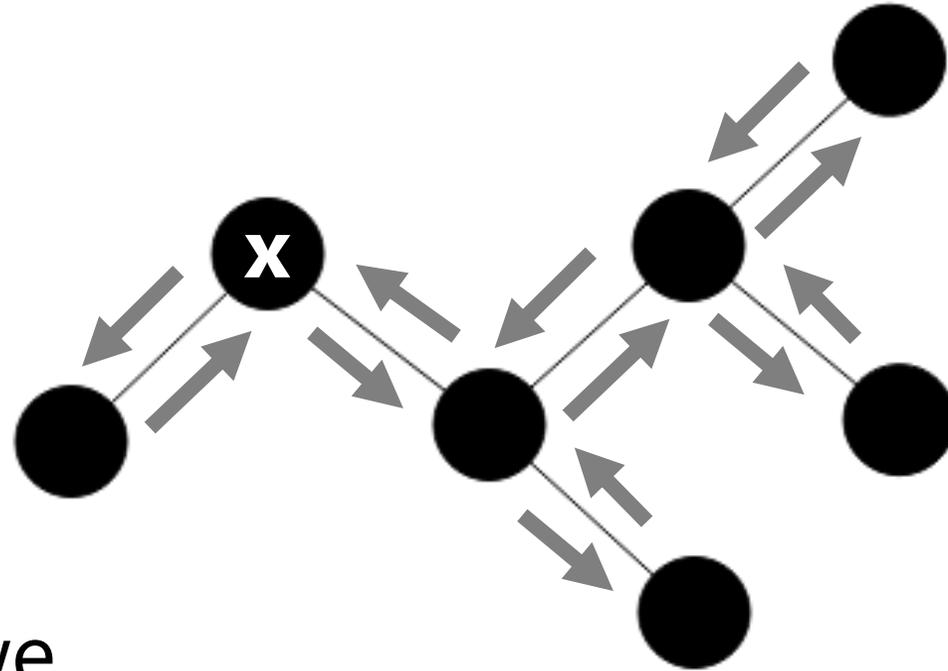
There are at most  $\Delta^s$  random walks of length  $s$  starting from  $x$

*However,* not all of these subgraphs can be covered by a random walk of length  $s$



See that a walk of length 6 starting at  $x$  **cannot** cover this subgraph of size 6

In  $2s$  steps, we can travel along **each edge in both directions**, ending at  $x$  again

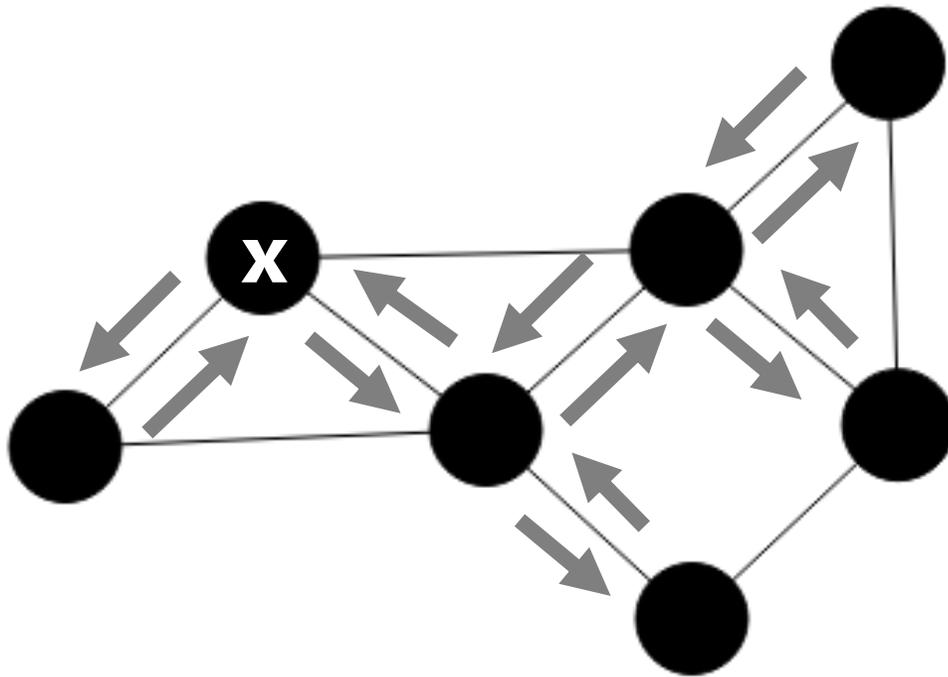


For any subgraph of size  $s$ , we will hit all vertices this way

(in this example, it looks like we're making an outline of the set)

There are at most  $\Delta^{2s}$  random walks of length  $2s$  starting from  $x$

(This method may *seem* to only work for 'tree-like' subgraphs)



but we can either consider the subgraph's **spanning tree** or remove edges until the subgraph is **minimally connected** to make it look 'tree-like')

(if you can already see why this method works for any subgraph of size  $s$  then this slide can be skipped!)

Therefore, our surjection instead reads as

**Random walks  
of length  $\underline{2s}$   
starting from  $x$**



**Connected  
sets of size  
 $s$  around  $x$**

(we send a walk of length  $\underline{2s}$  to the set of vertices it visited)

Hence there are at most  $\Delta^{2s}$  subgraphs of size  $s$  around  $x$

# Expander Graphs

And the Relaxation Time

Our result relies on the following Lemma<sup>1</sup>:

For a non-empty subset  $A$  and non-negative  $t$ ;

$$\mathbb{P}_\pi(T_A > t) \leq \pi(A^c) \exp\left(-\frac{t \cdot \pi(A)}{t_{\text{rel}}}\right)$$

where  $T_A = \inf\{t \geq 0 : X_t \in A\}$  is the first hitting time of the set  $A$  and the relaxation time is  $t_{\text{rel}} = \frac{1}{1-\lambda_2}$  where  $\lambda_2$  is the second largest eigenvalue of the transition matrix  $P$ . Note that, for a family of expander graphs,  $t_{\text{rel}}$  is uniformly bounded.

1. Riddhipratim Basu, Jonathan Hermon, and Yuval Peres. 'Characterization of cutoff for reversible Markov chains'. url: <http://dx.doi.org/10.1214/16-AOP1090>.

$$\mathbb{P}_\pi(T_A > t) \leq \pi(A^c) \exp\left(-\frac{t \cdot \pi(A)}{t_{\text{rel}}}\right)$$

We use this to **bound the probability of staying in a set**

(Since **leaving A** is the same as **hitting A<sup>c</sup>**)

Now, let's discuss **expander graphs**;

**Expander Graphs** satisfy the following;

In any small subset  $A$  of the graph, the number of **edges leaving the subset** is large - at least  $c|A|$  for a fixed constant  $c$

In an expander graph, **it is hard to stay within a small subset** because the graph is so well-connected

Studying expanders is useful because **randomly-generated** graphs are likely to be expanders

If we uniformly choose a  $d$ -regular graph with  $n$  vertices and choose some small enough  $\alpha > 0$  then the probability the graph will be an " $\alpha$ -expander" tends to 1 as  $n$  tends to infinity<sup>1</sup>

Additionally, they have bounds on their **relaxation time,  $t_{rel}$**  – this will be useful later!

1. Nathanaël Berestycki. 'Mixing Times of Markov Chains: Techniques and Examples'. url: <https://personal.math.ubc.ca/~jhermon/Mixing/mixing3.pdf>.

The result we found in this project is **especially strong for expander graphs**

It proves the **tight bound** mentioned by **Sauerwald et. al** for large enough walk-lengths

# A Bound for the Range of Random Walk Bridges

In relation to the Relaxation Time

*(The Result)*

Below is the result in full – don't worry about reading the fine print!

**Theorem 1.2.** *For all  $\Delta > 0$  there is a large enough constant  $C > 0$  such that for any graph  $G = (V, E)$  with degrees bounded by  $\Delta$  and  $|V| = n$ , for all even times  $t$  satisfying  $\frac{n}{2} \geq t \geq C t_{\text{rel}} \log n$ , where  $t_{\text{rel}}$  is the relaxation time of the simple random walk on  $G$ , we have that for all sufficiently small  $c$  there is a constant  $c'$  (depending on  $c$ ) such that*

$$\mathbb{P}_x \left( R_t > \frac{ct}{t_{\text{rel}}} \mid X_t = x \right) \geq 1 - e^{-c' \frac{t}{t_{\text{rel}}}}$$

where  $X_t$  is the simple random walk on  $G$  and  $R_t$  is its range.

The main strategy of the proof is to **bound the probability that a walk has at most range  $s$  at time  $t$**  by the probability that a walk of length  $t$  **stays inside some connected set of size  $s$**  containing the start vertex

Later, we'll replace  $s$  with something more useful

$$\mathbb{P}_x(R_t < s) \leq \sum_A \mathbb{P}_x(T_{A^c} > t)$$

(we use the union bound here)

We found that the **number of connected subsets of size  $s$  is upper-bounded by  $\Delta^{2s}$**

$$\sum_A \mathbb{P}_x(T_{A^c} > t) \leq \Delta^{2s} \max_A \mathbb{P}_x(T_{A^c} > t)$$

We then recall the lemma from earlier

$$\mathbb{P}_\pi(T_A > t) \leq \pi(A^c) \exp\left(-\frac{t \cdot \pi(A)}{t_{\text{rel}}}\right)$$

With some tampering...

$$\Delta^{2s} \max_A \mathbb{P}_x(T_{A^c} > t) \leq \Delta^{2s-1} s \cdot \exp\left(-\frac{t}{2\Delta \cdot t_{\text{rel}}}\right)$$

(there's a **lot** that I'm glossing over in this step)

We can then lazily re-introduce our conditioning and find that the **right-hand side tends to 0 in certain conditions**

$$\mathbb{P}_x(R_t < s \mid X_t = x) \leq \frac{\mathbb{P}_x(R_t < s)}{\mathbb{P}_x(X_t = x)} \leq \Delta^{2s} sn \cdot \exp\left(-\frac{t}{2\Delta \cdot t_{\text{rel}}}\right)$$

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A, B)}{\mathbb{P}(B)} \leq \frac{\mathbb{P}(A) \cdot \mathbb{P}(B|A)}{\mathbb{P}(B)} \leq \frac{\mathbb{P}(A)}{\mathbb{P}(B)}$$

We set  $s = c \frac{t}{t_{\text{rel}}}$  and find there exists some constant

$C > 0$  such that the right-hand side tends to 0 for  
 **$t \geq C t_{\text{rel}} \log n$**

$$\Delta^{2s} s n \cdot \exp\left(-\frac{t}{2\Delta \cdot t_{\text{rel}}}\right)$$

Therefore, the **probability that a closed random walk has range below  $ct/t_{\text{rel}}$  tends to 0** for  **$t \geq C t_{\text{rel}} \log n$**

$$\mathbb{P}_x \left( R_t < c \cdot \frac{t}{t_{\text{rel}}} \mid X_t = x \right) \rightarrow 0$$

This concludes the proof.



Remember expanders?

In a family of expanders, the **relaxation time**,  $t_{\text{rel}}$  is bounded

In the case of **expander graphs**, our result is strengthened. **For  $t \geq C \log n$ ,**

$$\mathbb{P}_x(R_t < c \cdot t \mid X_t = x) \rightarrow 0$$

This is a **tight bound** – it cannot be improved upon!

This concludes the presentation!

Thank you for listening!

If you want any more information, feel free to send an email to me at [ms2911@cam.ac.uk](mailto:ms2911@cam.ac.uk).